CLAIMS

- 1 1. A video system comprising:
- a video processing circuit that receives a picture and provides video compression
- 3 by using an optimal macroblock mode of operation, the optimal macroblock mode of
- 4 operation being identified by processing at least one macroblock of the picture, the
- 5 processing being performed independent of other macroblocks contained in the picture.
- 1 2. The video system of claim 1, wherein the video processing circuit includes an
- 2 encoder, the encoder comprising:
- a motion estimation circuit that identifies an optimal motion vector by processing
- 4 at least one macroblock contained in the picture, wherein the processing is carried out
- 5 independent of other macroblocks contained in the picture; and
- a mode selection circuit that identifies the optimal macroblock mode of operation.
- 1 3. The video system of claim 2, wherein the mode selection circuit identifies the
- 2 optimal macroblock mode of operation by using a rate-distortion model, where the rate-
- distortion model comprises an overall macroblock mode distortion D that is defined by a
- 4 model equation $D = D^{AC} + D^{DC}$, wherein D^{AC} is a distortion due to AC coefficients and
- 5 D^{DC} is a distortion due to DC coefficients.

- 1 4. The video system of claim 3, where D^{AC} is a model equation that is defined by
- 2 $D^{AC} = k_1 f(\sigma) g(R_{AC})$, wherein $f(\sigma)$ and $g(R_{AC})$ are two functions, σ is a measure of
- deviation of AC coefficients, R_{AC} is an allocated rate for encoding AC coefficients, and
- 4 k_I is a first numerical parameter that comprises at least one of a fixed number, an
- 5 estimated number, and a number that is dynamically determined during a frame of the
- 6 picture.
- 1 5. The video system of claim 4, when $f(\sigma) = \sigma^{k_2}$, wherein k_2 is a second numerical
- 2 parameter that comprises at least one of a fixed number, an estimated number, and a
- 3 number that is dynamically determined during a frame of the picture.
- 1 6. The video system of claim 4, when $g(R_{AC}) = e^{-k_3 R_{AC}}$, where k_3 is a third numerical
- 2 parameter that comprises at least one of a fixed number, an estimated number, and a
- 3 number that is dynamically determined during a frame of the picture.
- 1 7. The video system of claim 4, when R_{AC} is defined as
- $2 R_{AC} = R_{total} R_{hdr} R_{mv} R_{DC}, \text{ wherein } R_{total} \text{ is a target total number of bits for the at least}$
- one macroblock, R_{hdr} is a rate of encoding a header of the at least one macroblock, R_{mv} is
- a rate of motion vectors, and R_{DC} is a rate of the DC coefficients.
- 1 8. The video system of claim 3, wherein D^{DC} is calculated using a mean intensity
- 2 value over the at least one macroblock, and a quantization is carried out using a fixed step
- 3 size.

- 1 9. The video system of claim 3, wherein D^{DC} is equal to zero.
- 1 10. The video system of claim 3, wherein the optimal macroblock mode of operation
- 2 is selected as one that minimizes the overall macroblock mode distortion D.
- 1 11. The video system of claim 1, wherein the signal received from the video signal
- 2 source is at least one of a JPEG signal, an MPEG-x signal, and an ITU-specified H.26x
- 3 signal.
- 1 12. A method for video compression, the method comprising:
- 2 processing a picture by identifying an optimal macroblock mode of operation; and
- 3 processing a macroblock of the picture independent of other macroblocks
- 4 contained in the picture.
- 1 13. The method of claim 12, wherein identifying the optimal macroblock mode of
- 2 operation comprises:
- 3 providing a rate-distortion model;
- 4 computing a set of rate-distortion values using a set of macroblock modes of
- 5 operation upon the rate-distortion model;
- selecting from the set of rate-distortion values an optimal rate-distortion value;
- 7 and

- designating a macroblock mode of operation corresponding to the optimal rate-
- 9 distortion value as the optimal macroblock mode of operation.
- 1 14. The method of claim 13, further comprising identifying an optimal motion vector
- by processing one macroblock independent of other macroblocks contained in the picture.
- 1 15. The method of claim 14, wherein identifying the optimal motion vector
- 2 comprises:
- providing a first Lagrangian cost function equation that corresponds to the
- 4 macroblock;
- 5 incorporating a first Lagrangian multiplier into the first Lagrangian cost function
- 6 equation;
- 7 producing a set of Lagrangian cost functions by applying a set of motion vector
- 8 values to the first Lagrangian cost function equation that incorporates the first Lagrangian
- 9 multiplier;
- selecting a first optimal Lagrangian cost function from the set of Lagrangian cost
- 11 functions;
- selecting from the set of motion vector values a motion vector value that is
- associated with the first optimal Lagrangian cost function; and
- designating the selected motion vector value as the optimal motion vector value.

- 1 16. The method of claim 15, further comprising:
- 2 incorporating a set of Lagrangian multipliers into the first Lagrangian cost
- 3 function equation to generate a set of Lagrangian cost function equations;
- 4 identifying a set of motion vector values associated with a set of optimal
- 5 Lagrangian cost functions that are derived from the set of Lagrangian cost function
- 6 equations; and
- designating the set of motion vector values as the optimal set of motion vector
- 8 values.
- 1 17. The method of claim 16, wherein identifying the optimal macroblock mode of
- 2 operation comprises:
- 3 providing a rate-distortion model;
- 4 computing a set of rate-distortion values using a set of macroblock modes of
- 5 operation and the optimal set of motion vector values upon the rate-distortion model;
- 6 selecting from the set of rate-distortion values an optimal rate-distortion value;
- 7 and
- designating the macroblock mode of operation corresponding to the optimal rate-
- 9 distortion value as the optimal macroblock mode of operation.

- 1 18. A video processing program stored on a computer-readable medium, the video
- 2 processing program comprising:
- logic configured to provide a picture to the video processing program;
- 4 logic configured to provide a rate-distortion model; and
- logic configured to identify an optimal macroblock mode of operation by
- 6 processing a macroblock independent of other macroblocks contained in the picture.
- 1 19. The video processing program of claim 18, further comprising:
- logic configured to compute a set of rate-distortion values using a set of
- 3 macroblock modes of operation upon the rate-distortion model;
- 4 logic configured to select from the set of rate-distortion values an optimal rate-
- 5 distortion value; and
- 6 logic configured to designate a macroblock mode of operation corresponding to
- 7 the optimal rate-distortion value as the optimal macroblock mode of operation.
- 1 20. The video processing program of claim 18, further comprising logic configured to
- 2 identify an optimal motion vector by processing one macroblock independent of other
- 3 macroblocks contained in the picture.

21. The video processing program of claim 20 wherein the logic configured to 1 2 identify an optimal motion vector comprises: 3 logic configured to provide a first Lagrangian cost function equation that 4 corresponds to the macroblock; logic configured to incorporate a first Lagrangian multiplier into the first 5 Lagrangian cost function equation; 6 7 logic configured to produce a set of Lagrangian cost functions by applying a set of 8 motion vector values to the first Lagrangian cost function equation that incorporates the 9 first Lagrangian multiplier; 10 logic configured to select a first optimal Lagrangian cost function from the set of 11 Lagrangian cost functions; 12 logic configured to select from the set of motion vector values a motion vector 13 value that is associated with the first optimal Lagrangian cost function; and

logic configured to designate the selected motion vector value as the optimal

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motion vector value.

- 1 22. The video processing program of claim 21, further comprising:
- logic configured to incorporate a set of Lagrangian multipliers into the first
- 3 Lagrangian cost function equation to generate a set of Lagrangian cost function
- 4 equations;
- logic configured to identify a set of motion vector values associated with a set of
- 6 optimal Lagrangian cost functions that are derived from the set of Lagrangian cost
- 7 function equations; and
- logic configured to designate the set of motion vector values as the optimal set of
- 9 motion vector values.
- 1 23. The video processing program of claim 22, wherein the logic configured to
- 2 identify an optimal macroblock mode of operation comprises:
- logic configured to compute a set of rate-distortion values using a set of
- 4 macroblock modes of operation and the optimal set of motion vector values, upon the
- 5 rate-distortion model;
- logic configured to select from the set of rate-distortion values an optimal rate-
- 7 distortion value; and
- logic configured to designate the macroblock mode of operation corresponding to
- 9 the optimal rate-distortion value as the optimal macroblock mode of operation.